OpenRTM-aist (C++) - □□ #2418

EC□□RTC□□

05/07/2012 09:00 AM - n-ando

Status:	□□	**Start date:**	05/07/2012
Priority:	□□	**Due date:**	
Assignee:		**% Done:**	100%
Category:		**Estimated time:**	0.00 hour
Target version:			

Description

□□□EC□RTC□CORBA Object reference□□
□□□□□□□onExecute□□□

Associated revisions

Revision 2355 - 05/07/2012 11:08 AM - n-ando

Now RTObjectStateMachine object calls RTC's callbacks via servant if it is available. refs #2418

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History

#1 - 05/07/2012 09:01 AM - n-ando

OmniORB□□□□□□□□□□□□□□□□□□□□□□

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#2 - 05/07/2012 09:06 AM - n-ando

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```
interface Hoge
{
  void munya(in string msg, in short val);
};
```

```
//
// CORBA performance test program
//    Noriaki Ando, 2012.4.18
//
// This program compare between CORBA servant (implementation)
// operation call and CORBA object reference operation call.
//
// 1. Servant newed from Hoge_impl
// 2. Object reference obtained by _this()
// 3. Object reference from stringfied IOR
// 4. Servant obtained from object reference by reference_to_servant
//
// Servant.
// 0[sec], 3571[usec]
```

```
// Object reference from _this().
// 0[sec], 150894[usec]
// Created object from string IOR.
// 0[sec], 143678[usec]
// Servant obtained from reference_to_servant.
// 0[sec], 3543[usec]
// ORB termianted.
//
// Servant :   3.571 ns
// Obj ref : 150.894 ns
// IOR ref : 143.678 ns
// Servant2:   3.543 ns
// obj ref is 42 times slower than servant
//
#include <omniORB4/CORBA.h>
#include <sys/time.h>
#include <iostream>
#include <pthread.h>

#include "hoge.hh"
CORBA::ORB_var orb;
class Hoge_impl
  : public virtual POA_Hoge
{
public:
  virtual void munya(const char* msg, ::CORBA::Short val)
  {
    //    std::cout << msg << std::endl;
    return;
  }
};
void* orb_run(void* arg)
{
  std::cout << "orb started" << std::endl;
  orb->run();
  return NULL;
}

#define USEC_PAR_SEC 1000000
timeval subtime(timeval start, timeval end)
{
  timeval ret;
  if (end.tv_usec < start.tv_usec)
    {
      ret.tv_usec = end.tv_usec + USEC_PAR_SEC - start.tv_usec;
      ret.tv_sec = end.tv_sec - 1 - start.tv_sec;
      return ret;
    }

  ret.tv_usec = end.tv_usec - start.tv_usec;
  ret.tv_sec = end.tv_sec - start.tv_sec;
  return ret;
}

int main(int argc, char** argv)
{
   orb = CORBA::ORB_init(argc, argv);
   CORBA::Object_var obj = orb->resolve_initial_references((char*)"RootPOA");
   PortableServer::POA_var poa = PortableServer::POA::_narrow(obj);
   PortableServer::POAManager_var poamgr = poa->the_POAManager();
   poamgr->activate();

//   pthread_t thread_handle;
//   pthread_attr_t thread_attr;
//   pthread_create(&thread_handle, NULL, orb_run, (void *) NULL);

   Hoge_impl* hoge_servant = new Hoge_impl();
   CORBA::Object_var hoge_obj = hoge_servant->_this();
   Hoge_var hoge_var = Hoge::_narrow(hoge_obj);
   std::string ior;
   ior = orb->object_to_string(hoge_var);
   std::cout << ior << std::endl;

   CORBA::Object_var newobj = orb->string_to_object(ior.c_str());
   Hoge_var newhoge = Hoge::_narrow(newobj);
```

```
  Hoge_impl* newservant
    = dynamic_cast<Hoge_impl*>(poa->reference_to_servant(hoge_var));

  timeval start, end, result;

  gettimeofday(&start, NULL);
  for (int i(0); i < 1000000; ++i)
    {
      hoge_servant->munya("hoge", 1000);
    }
  gettimeofday(&end, NULL);
  result = subtime(start, end);
  std::cout << "Servant." << std::endl;
  std::cout << result.tv_sec << "[sec], ";
  std::cout << result.tv_usec << "[usec]" << std::endl;

  gettimeofday(&start, NULL);
  for (int i(0); i < 1000000; ++i)
    {
      hoge_var->munya("hoge", 1000);
    }
  gettimeofday(&end, NULL);
  result = subtime(start, end);
  std::cout << "Object reference from _this()." << std::endl;
  std::cout << result.tv_sec << "[sec], ";
  std::cout << result.tv_usec << "[usec]" << std::endl;

  gettimeofday(&start, NULL);
  for (int i(0); i < 1000000; ++i)
    {
      newhoge->munya("hoge", 1000);
    }
  gettimeofday(&end, NULL);
  result = subtime(start, end);
  std::cout << "Created object from string IOR." << std::endl;
  std::cout << result.tv_sec << "[sec], ";
  std::cout << result.tv_usec << "[usec]" << std::endl;

  gettimeofday(&start, NULL);
  for (int i(0); i < 1000000; ++i)
    {
      newservant->munya("hoge", 1000);
    }
  gettimeofday(&end, NULL);
  result = subtime(start, end);
  std::cout << "Servant obtained from reference_to_servant." << std::endl;
  std::cout << result.tv_sec << "[sec], ";
  std::cout << result.tv_usec << "[usec]" << std::endl;

  //   orb->shutdown(true);
  //   pthread_join(thread_handle, NULL);
  //   std::cout << "ORB termianted." << std::endl;

  return 0;
}
```

```
all: hoge

OBJS = hogeSK.o hoge_impl.o
CFLAGS = -I.
LIBS = -lomniORB4 -lomnithread

hoge: $(OBJS)
    g++ -o hoge $(OBJS) $(LIBS)

hogeSK.o: hogeSK.cc
    g++ $(CFLAGS) -c -o hogeSK.o hogeSK.cc

hoge_impl.o: hoge_impl.cpp
    g++ $(CFLAGS) -c -o hoge_impl.o hoge_impl.cpp
```

```
hogeSK.cc: hoge.idl
    omniidl -bcxx hoge.idl

clean:
    rm -rf *.o hogeSK.cc hoge.hh hoge core *~
```

□ □

Servant	3.571 ns	□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□
Obj ref	150.894 ns	_this()□□□□□□□□□□□□□□□□□□□□□□□□□□□□
IOR ref	143.678 ns	IOR□□□□□□□□□□□□□□□□□□□□□□□
Servant2	3.543 ns	IOR->□□□□□□□□□->reference_to_servant□□□□□ □□□□□□□□□□

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#3 - 05/07/2012 11:06 AM - n-ando

RTObjectStateMachine□□

```
Index: RTObjectStateMachine.cpp

===================================================================

--- RTObjectStateMachine.cpp    (revision 2330)

+++ RTObjectStateMachine.cpp    (working copy)

@@ -17,6 +17,8 @@

  */

 #include <rtm/RTObjectStateMachine.h>
+#include <rtm/Manager.h>
+#include <rtm/RTObject.h>
 #include <iostream>
 #include <stdio.h>

@@ -27,7 +29,8 @@

     : m_id(id),
       m_rtobj(RTC::LightweightRTObject::_duplicate(comp)),
       m_sm(NUM_OF_LIFECYCLESTATE),
-      m_ca(false), m_dfc(false), m_fsm(false), m_mode(false)
+      m_ca(false), m_dfc(false), m_fsm(false), m_mode(false),
```

```
+      m_rtobjPtr(NULL), m_measure(false)
   {
     m_caVar   = RTC::ComponentAction::_nil();
     m_dfcVar  = RTC::DataFlowComponentAction::_nil();
@@ -155,7 +158,11 @@

   setComponentAction(const RTC::LightweightRTObject_ptr comp)
   {
     m_caVar = RTC::ComponentAction::_narrow(comp);
-    if (!CORBA::is_nil(m_caVar)) { m_ca = true; }
+    if (CORBA::is_nil(m_caVar)) { return; }
+    m_ca = true;
+    PortableServer::POA_ptr poa = RTC::Manager::instance().getPOA();
+    m_rtobjPtr =
+      dynamic_cast<RTC::RTObject_impl*>(poa->reference_to_servant(comp));
   }

   void RTObjectStateMachine::
@@ -182,16 +189,40 @@

   // RTC::ComponentAction operations
   void RTObjectStateMachine::onStartup(void)
   {
+    // call Servant
+    if (m_rtobjPtr != NULL)
+      {
+        m_rtobjPtr->on_startup(m_id);
+        return;
+      }
+    // call Object reference
     if (!m_ca) { return; }
     m_caVar->on_startup(m_id);
   }
   void RTObjectStateMachine::onShutdown(void)
   {
+    // call Servant
+    if (m_rtobjPtr != NULL)
+      {
+        m_rtobjPtr->on_shutdown(m_id);
+        return;
+      }
+    // call Object reference
     if (!m_ca) { return; }
     m_caVar->on_shutdown(m_id);
   }
   void RTObjectStateMachine::onActivated(const ExecContextStates& st)
   {
+    // call Servant
+    if (m_rtobjPtr != NULL)
+      {
+        if (m_rtobjPtr->on_activated(m_id) != RTC::RTC_OK)
+          {
+            m_sm.goTo(RTC::ERROR_STATE);
+          }
+        return;
+      }
+    // call Object reference
     if (!m_ca) { return; }
     if (m_caVar->on_activated(m_id) != RTC::RTC_OK)
       {
@@ -203,24 +234,55 @@

   void RTObjectStateMachine::onDeactivated(const ExecContextStates& st)
   {
+    // call Servant
+    if (m_rtobjPtr != NULL)
+      {
+        m_rtobjPtr->on_deactivated(m_id);
+        return;
+      }
+    // call Object reference
     if (!m_ca) { return; }
     m_caVar->on_deactivated(m_id);
   }
```

```
   void RTObjectStateMachine::onAborting(const ExecContextStates& st)
   {
+    // call Servant
+    if (m_rtobjPtr != NULL)
+      {
+        m_rtobjPtr->on_aborting(m_id);
+        return;
+      }
+    // call Object reference
     if (!m_ca) { return; }
-    m_caVar->on_error(m_id);
+    m_caVar->on_aborting(m_id);
   }

   void RTObjectStateMachine::onError(const ExecContextStates& st)
   {
+    // call Servant
+    if (m_rtobjPtr != NULL)
+      {
+        m_rtobjPtr->on_error(m_id);
+        return;
+      }
+    // call Object reference
     if (!m_ca) { return; }
     m_caVar->on_error(m_id);
   }

   void RTObjectStateMachine::onReset(const ExecContextStates& st)
   {
+    // call Servant
+    if (m_rtobjPtr != NULL)
+      {
+        if (m_rtobjPtr->on_reset(m_id) != RTC::RTC_OK)
+          {
+            m_sm.goTo(RTC::ERROR_STATE);
+          }
+        return;
+      }
+    // call Object reference
     if (!m_ca) { return; }
     if (m_caVar->on_reset(m_id) != RTC::RTC_OK)
       {
@@ -233,9 +295,58 @@

   // RTC::DataflowComponentAction
   void RTObjectStateMachine::onExecute(const ExecContextStates& st)
   {
+    static int count;
+    double max_interval, min_interval, mean_interval, stddev;
+    // call Servant
+    if (m_rtobjPtr != NULL)
+      {
+        if (m_measure) { m_svtMeasure.tick(); }
+        if (m_rtobjPtr->on_execute(m_id) != RTC::RTC_OK)
+          {
+            m_sm.goTo(RTC::ERROR_STATE);
+          }
+        if (m_measure)
+          {
+            m_svtMeasure.tack();
+            if (count > 1000)
+              {
+                count = 0;
+                m_svtMeasure.getStatistics(max_interval, min_interval,
+                                           mean_interval, stddev);
+                std::cout << "[servant] ";
+                std::cout << " max: "    << max_interval;
+                std::cout << " min: "    << min_interval;
+                std::cout << " mean: "   << mean_interval;
+                std::cout << " stddev: " << stddev;
+                std::cout << std::endl;
+              }
+            ++count;
+          }
+        return;
```

```
+      }
+    // call Object reference
     if (!m_dfc) { return; }
-    if (m_dfcVar->on_execute(m_id) != RTC::RTC_OK)
+    if (m_measure) { m_refMeasure.tick(); }
+    RTC::ReturnCode_t ret = m_dfcVar->on_execute(m_id);
+    if (m_measure)
       {
+        m_refMeasure.tack();
+        if (count > 1000)
+          {
+            count = 0;
+            m_refMeasure.getStatistics(max_interval, min_interval,
+                                       mean_interval, stddev);
+            std::cout << "[objref] ";
+            std::cout << " max: "    << max_interval;
+            std::cout << " min: "    << min_interval;
+            std::cout << " mean: "   << mean_interval;
+            std::cout << " stddev: " << stddev;
+            std::cout << std::endl;
+          }
+        ++count;
+      }
+    if (ret != RTC::RTC_OK)
+      {
+        m_sm.goTo(RTC::ERROR_STATE);
         return;
       }
@@ -244,6 +355,16 @@

   void RTObjectStateMachine::onStateUpdate(const ExecContextStates& st)
   {
+    // call Servant
+    if (m_rtobjPtr != NULL)
+      {
+        if (m_rtobjPtr->on_state_update(m_id) != RTC::RTC_OK)
+          {
+            m_sm.goTo(RTC::ERROR_STATE);
+          }
+        return;
+      }
+    // call Object reference
     if (!m_dfc) { return; }
     if (m_dfcVar->on_state_update(m_id) != RTC::RTC_OK)
       {
@@ -255,6 +376,16 @@

   void RTObjectStateMachine::onRateChanged(void)
   {
+    // call Servant
+    if (m_rtobjPtr != NULL)
+      {
+        if (m_rtobjPtr->on_rate_changed(m_id) != RTC::RTC_OK)
+          {
+            m_sm.goTo(RTC::ERROR_STATE);
+          }
+        return;
+      }
+    // call Object reference
     if (!m_dfc) { return; }
     if (m_dfcVar->on_rate_changed(m_id) != RTC::RTC_OK)
       {
```

#4 - 05/07/2012 11:16 AM - n-ando

- Status changed from □□ to □□

- % Done changed from 0 to 100

□□□□□□□□□□□□□□□

- ConfigSampleComp
  - EC: nowait
  - □□□□□□□□
  - log: NO, loglevel: NORMAL
  - 1000□□□□□□□

objref	17us
servant	2.5us

7□□□□□□□□□□□□□□□CORBA□□□□□□□□□□□□□□□□□□□□40□□□□□□□□□□□□□□□□□□□□
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#5 - 05/07/2012 11:19 AM - n-ando

- File 120419_newEC.zip added

#6 - 05/07/2012 11:19 AM - n-ando

- Status changed from □□ to □□

Files

120419_newEC.zip	1.5 MB	05/07/2012	n-ando