



```

→
["RTC0.port0","RTC0.port1"]

comp_ports
comp0_name = comp_ports [0].split(".")[0]
→
["RTC0","port0"]

comp0_name
comp0 = self.getComponent(comp0_name)
port0_var = OpenRTM_aist.CORBA_RTCUtil.get_port_by_name(comp0.getObjRef(), comp_ports [0])

conn_prop [1]
opt_props = conn_prop [1].split("&")
→
["interface_type=corba_cdr","dataport.dataflow_type=pull"]

opt_props
temp = o.split("=")
→
["interface_type","corba_cdr"]

prop.setProperty("dataport."+temp [0],temp [1])

OpenRTM_aist.CORBA_RTCUtil.connect(c, prop, port0_var, port1_var)

initPreConnection activateManager rtc.conf
manager.components.precreate RTC

MyModuleInit TestComp10 TestComp20 in out service

setUp
self.dataPortConnectorName = "TestComp20.in:TestComp10.out(interface_type=direct)"
self.servicePortConnectorName = "TestComp10.service:TestComp20.service()"
sys.argv.extend(['-o', 'manager.components.preconnect:'+self.dataPortConnectorName+', '+self.servicePortConnectorName])

self.manager = OpenRTM_aist.Manager.init(sys.argv)
self.manager.setModuleInitProc(MyModuleInit)
self.manager.activateManager()

→MyModuleInit TestComp10 TestComp20 in out service

test_PreConnection
ans = OpenRTM_aist.already_connected(inport, outport)
self.assertTrue(ans)

self.assertEqual(prop.getProperty("dataport.interface_type"),"direct")

ans = OpenRTM_aist.already_connected(provided, required)
self.assertTrue(ans)

```

