OpenRTM-aist (C++) - □□ #3656

RTC□□□

10/11/2016 01:52 PM - n-miyamoto

Status:	□□		**Start date:**	10/11/2016
Priority:	□□		**Due date:**	10/31/2016
Assignee:	n-miyamoto		**% Done:**	100%
Category:			**Estimated time:**	0.00 hour
Target version:				

Description

□□□□□□□□rtc.conf□□□□□□□□□□□□□□□□□□□□□RTC□□□□□□□□□□□□□□1□□□□□□□□□□□□□□□□□RTC□□□(PeriodicExecutionContext)□□□□□□

Associated revisions

Revision 2776 - 10/12/2016 11:50 PM - n-ando

[compat,RELENG_1_2] Indentation has been modified. refs #3656

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[compat,RELENG_1_2] Indentation has been modified. refs #3656

History

#1 - 10/12/2016 12:18 PM - n-miyamoto

- Status changed from □□ to □□

- % Done changed from 0 to 100

createContexts□□□□□□□□□□□□□□□□□□□□□□□□o□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□

```
    if (m_eclist.empty())
    {

        coil::Properties prop;
        prop.setDefaults(default_config);
        RTC::ExecutionContextBase* ec = NULL;
        ec = RTC::ExecutionContextFactory::
            instance().createObject(prop["exec_cxt.periodic.type"].c_str());
        if (ec == NULL)
        {
            RTC_ERROR(("EC (%s) creation failed.", prop["exec_cxt.periodic.type"].c_str()));
            RTC_DEBUG(("Available EC list: %s",
                coil::flatten(avail_ec).c_str()));
            ret = RTC::RTC_ERROR;
        }

        ec->init(coil::Properties());
        m_eclist.push_back(ec);
        ec->bindComponent(this);
    }
```

□□□□□□□□□□□□□□□□□□DefaultConfiguration.h□□□□□□□□□□□□□□□□□□DefaultConfiguration.h□□□version.h□□□□□□static
c□□□□□□□□□□□□□□□□□

```
    echo 'static const char* openrtm_name    = "'${PACKAGE}'-'${VERSION}'";' >> $@
    echo 'static const char* openrtm_version = "'${VERSION}'";' >> $@
```

```
     echo 'static const char* corba_name       = "'${ORB}'";' >> $@
```

#2 - 08/30/2017 12:17 PM - n-ando

- Status changed from □□ to □□