RTC Builder - □□ #3977

IDL□□□

03/07/2017 03:35 PM - n.kawauchi

Status:	□□		**Start date:**	03/07/2017
Priority:	□□		**Due date:**	
Assignee:	ga		**% Done:**	100%
Category:			**Estimated time:**	0.00 hour
Target version:	RELEASE_1_2_0			

Description

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  https://github.com/Nobu19800/RobotArmController/issues/1

- Linux□□ + CMake3.7.2 □□□□□□□□□□□□□□□□□□□□□□IDL□□□□□□□□□□□□□□□□□□□□□□□□□□□□□
- IDL□□
- RTC Builder□□□□□□src/CMakeLists.txt□□□${PROJECT_NAME}Comp□□□□□□ALL_IDL_TGT□□□□□□□□□□□□□□□□□□
- src/CMakeLists.txt □ add_dependencies(${PROJECT_NAME}Comp ALL_IDL_TGT) □□□□□□□□□□□□□□□□
- ImageProcessing□ImageCalibration□C++ RTC□□□□□□□□□□□□□□□□□□□□□□□

```
set_target_properties(${PROJECT_NAME} PROPERTIES PREFIX "")
set_source_files_properties(${ALL_IDL_SRCS} PROPERTIES GENERATED 1)
add_dependencies(${PROJECT_NAME} ALL_IDL_TGT)
target_link_libraries(${PROJECT_NAME} ${OPENRTM_LIBRARIES} ${OpenCV_LIBS})

add_executable(${PROJECT_NAME}Comp ${standalone_srcs}
  ${comp_srcs} ${comp_headers} ${ALL_IDL_SRCS})
add_dependencies(${PROJECT_NAME}Comp ALL_IDL_TGT)□←★
target_link_libraries(${PROJECT_NAME}Comp ${OPENRTM_LIBRARIES} ${OpenCV_LIBS})
```

Associated revisions

Revision 698 - 03/11/2017 12:14 PM - ga

Modified generated CMakeFile #3977

History

#1 - 03/11/2017 12:15 PM - ga

- Status changed from □□ to □□

- % Done changed from 0 to 100

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#2 - 03/15/2017 02:09 PM - n.kawauchi

r702□□□□□□□□OpenRTP□□□□□□□□□□□□□□□□□□□□□□□□□□myImageCalibration(C++ RTC)□□□□□
□□□RTC□ Ubuntu14.04 + CMake3.7.2 □□□□□□□□□□□□□□□□□□□□□□□□□□□
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#3 - 03/17/2017 09:38 AM - n-ando

- Status changed from □□ to □□